#### A Fundamental Tool: the Poincaré-Pontryagin Theorem



- Poincaré first return map P(h)
- Displacement d(h) = P(h) h
- Limit cycle  $\Leftrightarrow$  isolated zero of d
- Abelian integral  $\mathcal{I}(h)$ :

$$\oint_{H^{-1}(h)} f(x,y) \mathrm{d}y - g(x,y) \mathrm{d}x$$

#### Poincaré-Pontryagin theorem

The Abelian integral  $\mathcal{I}(h)$  approximates the displacement function d(h) for small  $\varepsilon$ :

$$\dot{x} = -\partial_y H(x, y) + \varepsilon f(x, y)$$
  
 $\dot{y} = \partial_x H(x, y) + \varepsilon g(x, y)$ 

$$d(h) = \varepsilon(\mathcal{I}(h) + O(\varepsilon))$$
 when  $\varepsilon o 0$ 

limit cycles  $\equiv$  changes of sign of  $\mathcal{I}(h) \equiv$  simple zeros of  $\mathcal{I}(h)$ 

• Hamiltonian system:

$$\begin{cases} \dot{x} = -4y(y^2 - 1.1) \\ \dot{y} = 4x(x^2 - 0.9) \end{cases}$$



• pseudo-Hamiltonian system:

$$\begin{cases} \dot{x} = -4yy(y^2 - 1.1) \\ \dot{y} = 4yx(x^2 - 0.9) \end{cases}$$



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same geometric orbits after rescaling

•  $\simeq$  perturbations without rescaling:  $\frac{f(x, y)}{y}, \frac{g(x, y)}{y} \in \langle x^i y^j, i \ge 0, j \ge -1, i+j \le 3$ 



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Generalized Poincaré-Pontryagin theorem

The generalized Abelian integral:

$$\mathcal{I}(h) = \oint_{H^{-1}(h)} \frac{f(x, y) \mathrm{d}y - g(x, y) \mathrm{d}x}{y}$$

approximates the displacement function d(h) for small  $\varepsilon$ :

$$d(h) = arepsilon (\mathcal{I}(h) + O(arepsilon)) \qquad ext{when } arepsilon o 0$$



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 $\Rightarrow$  Maximize the number of zeros of  $\mathcal{I}(h)$ 

polynomial or rational functions  

$$\int f(x, y) dy - g(x, y) dx$$

$$\int f(h) \quad \text{oval } H(x, y) = h \text{ with } H \text{ polynomial or rational}$$

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- o High accuracy evaluation in good complexity
- o Rigorous and tight error bounds

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$$f(x,y) = 1 \quad x \quad y \quad x^2 \quad xy \\ y^2 \quad x^3 \quad x^2y \quad xy^2 \quad y^3 \\ x^4 \quad x^3y \quad x^2y^2 \quad xy^3 \quad y^4 \\ g(x,y) = 1 \quad x \quad y \quad x^2 \quad xy \\ y^2 \quad x^3 \quad x^2y \quad xy^2 \quad y^3 \\ x^4 \quad x^3y \quad x^2y^2 \quad xy^3 \quad y^4 \\ \end{cases}$$

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$$\mathcal{I}(h) = \oint_{H^{-1}(h)} \frac{\alpha_{00} + \alpha_{20}x^2 + \alpha_{22}x^2y^2 + \alpha_{40}x^4 + \alpha_{04}y^4}{y} dx$$

• Find coefficients of  $\mathcal{I}(h) = \alpha_{00}\mathcal{I}_{00}(h) + \alpha_{20}\mathcal{I}_{20}(h) + \alpha_{22}\mathcal{I}_{22}(h) + \alpha_{40}\mathcal{I}_{40}(h) + \alpha_{04}\mathcal{I}_{04}(h)$ 



9

$\alpha_{00}$	=	-0.78622148667854837664
$\alpha_{20}$	=	0.87723523612653436051
$\alpha_{22}$	=	1
$\alpha_{40}$	=	0.23742713894293038223
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 $4 \times 5 + 2 \times 2 = 24$ 

$$H(x, y) = (x^2 - 0.9)^2 + (y^2 - 1.1)^2$$

$$0 < \sqrt{h} =: r < 0.9$$



$$H(x,y) = (x^2 - 0.9)^2 + (y^2 - 1.1)^2 \qquad \qquad 0 < \sqrt{h} =: r < 0.9$$





$$\begin{aligned} x_{\min} &= \sqrt{0.9 - \frac{r}{\sqrt{2}}} & x_{\max} &= \sqrt{0.9 + \frac{r}{\sqrt{2}}} \\ y_{\min} &= \sqrt{1.1 - \frac{r}{\sqrt{2}}} & y_{\max} &= \sqrt{1.1 + \frac{r}{\sqrt{2}}} \end{aligned}$$

$$H(x,y) = (x^2 - 0.9)^2 + (y^2 - 1.1)^2 \qquad \qquad 0 < \sqrt{h} =: r < 0.9$$





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$$H(x, y) = (x^{2}-0.9)^{2} + (y^{2}-1.1)^{2} \qquad 0 < \sqrt{h} =: r < 0.9$$

$$x_{\min} = \sqrt{0.9 - \frac{r}{\sqrt{2}}} \qquad x_{\max} = \sqrt{0.9 + \frac{r}{\sqrt{2}}}$$

$$y_{\min} = \sqrt{1.1 - \frac{r}{\sqrt{2}}} \qquad y_{\max} = \sqrt{1.1 + \frac{r}{\sqrt{2}}}$$

$$y_{up}(x) = \sqrt{1.1 + \sqrt{r^{2} - (x^{2} - 0.9)^{2}}}$$

$$y_{down}(x) = \sqrt{1.1 - \sqrt{r^{2} - (x^{2} - 0.9)^{2}}}$$

$$y_{down}(x) = \sqrt{1.1 - \sqrt{r^{2} - (x^{2} - 0.9)^{2}}}$$

$$x_{left}(y) = \sqrt{0.9 - \sqrt{r^{2} - (y^{2} - 1.1)^{2}}}$$

$$x_{right}(y) = \sqrt{0.9 + \sqrt{r^{2} - (y^{2} - 1.1)^{2}}}$$

$$I(h) = \oint_{H^{-1}(h)} \frac{g(x, y)}{y} dx = \int_{x_{min}}^{x_{max}} \left(\frac{g(x, y_{up}(x))}{y_{up}(x)} - \frac{g(x, y_{down}(x))}{y_{down}(x)}\right) dx$$

$$+ \int_{y_{min}}^{y_{max}} \left(\frac{g(x_{left}(y), y)}{x_{left}(y)} + \frac{g(x_{right}(y), y)}{x_{right}(y)}\right) \frac{y^{2} - 1.1}{\sqrt{r^{2} - (y^{2} - 1.1)^{2}}} dy._{10}$$

dx

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$$0.9 < \sqrt{h} =: r < 1.1$$



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$$\begin{aligned} x_{\min} &= 0 & x_{\max} = \sqrt{0.9 + \frac{r}{\sqrt{2}}} \\ y_{\min} &= \sqrt{1.1 - \frac{r}{\sqrt{2}}} & y_{\max} = \sqrt{1.1 + \frac{r}{\sqrt{2}}} \\ y_{up}(x) &= \sqrt{1.1 + \sqrt{r^2 - (x^2 - 0.9)^2}} \\ y_{down}(x) &= \sqrt{1.1 - \sqrt{r^2 - (x^2 - 0.9)^2}} \\ x_{left}(y) &= \sqrt{0.9 - \sqrt{r^2 - (y^2 - 1.1)^2}} \\ x_{right}(y) &= \sqrt{0.9 + \sqrt{r^2 - (y^2 - 1.1)^2}} \end{aligned}$$

$$\begin{split} f) &= \oint_{H^{-1}(h)} \frac{g(x,y)}{y} dx = \int_{-x_{max}}^{x_{max}} \left( \frac{g(x,y_{up}(x))}{y_{up}(x)} - \frac{g(x,y_{down}(x))}{y_{down}(x)} \right) dx \\ &+ 2 \int_{y_{min}}^{y_{max}} \frac{g(x_{right}(y),y)(y^2 - 1.1)}{x_{right}(y)\sqrt{r^2 - (y^2 - 1.1)^2}} dy. \end{split}$$

# A bit of Coq code